

# More Precision

boreCONTROL Sensor // Non-contact inspection of bore holes



# Non-contact inspection of bore holes

## boreCONTROL Sensor



- Non-contact measurement
- Measurement of a wide variety of materials, also sensitive surfaces
- High precision and detailed statements about dimensions and quality of interior walls
- Short measurement cycles due to high sampling rate
- Large measuring ranges
- Fast setup

### Non-contact measurement of diameter in cylindrical geometries

The boreCONTROL sensor is designed for non-contact diameter measurement and surface assessment. The sensor is easy to set up and configure, providing high precision statements about the quality of bore holes or cavities in the diameter range from 4mm up to 16mm.

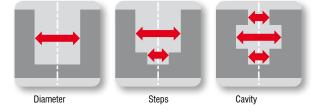
# Measuring procedure

The underlying confocal chromatic measuring principle offers the following advantages:

- Non-contact measurement with small light spot
- High resolution in radial & axial direction
- High dynamics (sampling rate up to 25kHz)
- Applicable for most diverse materials

### **Applications**

- Measurement of rivet holes in aircraft construction
- Surface assessment & defect detection
- For numerous applications in the automotive industry, aircraft industry, medical engineering and in machine building





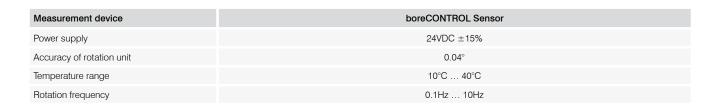








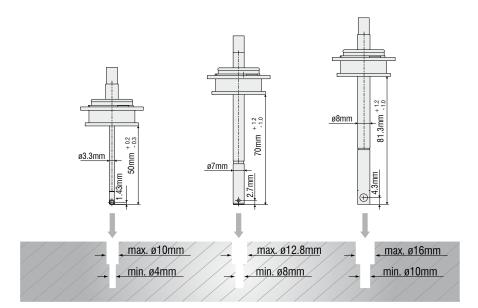


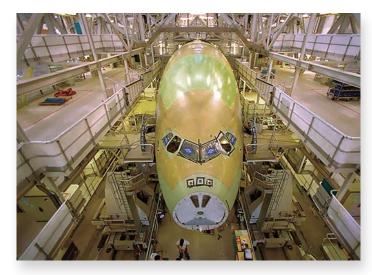


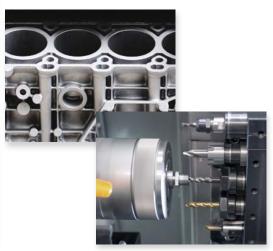
Sensor lance	BCS2412-4/10	BCS2412-8/12,8	BCS2413-10/16
Measurable diameters	4 - 10mm	8 - 12.8mm	10 - 16mm
Sampling rate	max. 25kHz	max. 25kHz	max. 25kHz
Measurement spot diameter 1)	approx. 40µm	approx. 30µm	approx. 30µm
Dynamic repeatability 2)	± 1μm	± 1 $\mu$ m	$\pm$ 1 $\mu$ m
Linearity <sup>2)</sup> Ø	± 5µm	± 5μm	± 5μm

<sup>1)</sup> In the midrange

As the accuracy varies with different surfaces and their properties, we recommend you contact us directly. We will be pleased to check the technical feasibility of your measurement task.







<sup>&</sup>lt;sup>2)</sup> Specified accuracy to the following general conditions: min. sampling rate 1kHz; 60 rotations (repetitions) within 1 min; temperature drift: <1K/h; calibration ring (DIN 2250C), accuracy of center position ±50µm;</p>

### System Components

The boreCONTROL sensor consists of a rotating unit with exchangeable sensor lance, motor controller and sensor controller. The rotary drive is operated by the motor controller. The sensor controller serves for set-up and signal processing.

Via the Ethernet interface of the controller, boreCONTROL provides a data package with distance, angle and intensity figures. For customer software development, a SDK is included.

# Parameter set up and signal processing Data output via Ethernet BCC2410 motor controller BCM2410 rotating unit BCS241x sensor lance BCM2410 rotating unit BCS241x sensor lance BCM2410 rotating unit Parameter set up and signal processing Data output via Ethernet Controls the rotating unit Provides the sensor controller with angle information BCM2410 rotating unit BCM2410 rotating unit BCS241x sensor lance BCM2410 rotating unit BCS241x sensor lance

Software:

boreCONTROL SDK Software Development Kit for customer software integration (included in scope of supply)

Accessories:

C2400/PT-x Optical-fiber cable (3m,5m,10m, customer-specific length up to 25m; optionally suitable for use with robots)
PC2410-x Power supply and signal cable (3m, 5m,10m, customer-specific length up to 25m, optionally suitable for use

with robots)

SC2410-0,5 Synchronization cable (0.5m)
One-Click-Cleaner Cleans the optical connections

Optional accessories:

BCS2412-4/10 Dummy sensor For customer simulation of z movement during machine or robot setup BCS2412-8/12.8 Dummy sensor For customer simulation of z movement during machine or robot setup For customer simulation of z movement during machine or robot setup

MA2400-45 Mounting adapter for rotating unit

Y adapter cable for encoder Cable for encoder signal input of customer-specific linear axis (z movement of sensor) into the IFC2461

controller

PS2020 Power supply 24V / 2.5A