





## Technical data

• Nominal torque: 50 Nm to 2.000 Nm, bidirectional

Rotational speed: ≤ 10.000 rpm

• Accuracy: ≤ ±0,2 %

Temperature range: -40 °C to +85 °C

Protection class: IP50, IP65
Output signals: 0-10 V/4-20 mA
Output frequency: 2.500 Hz

## Your advantages

Made in Germany (Munich, Bavaria)

Delivery ex warehouse (< two weeks)</li>

• Best price-performance ratio

Integrated electronic (Plug & Play)

Contactless measurement system

Including 5 m cable and calibration certificate

## **Short description**

The series 3000 covers the accurate and reliable professional torque measurement technology.

This series is mainly used in laboratory, test facilities, trials, medical engineering, process monitoring and quality control.

Transmitted torque can be measured statically and dynamically in real time. Shaft is available as Round shaft and Square shaft. Each sensor can be configured individually with a lot of extras, such as angle sensor and protection class IP65.

Series 3000 offers different output signals such as 0-10 V, 4-20 mA.

The sensor is provided as a complete unit with integrated evaluation electronic, including 5 m cable, keystones (Round shaft) and calibration certificate.





### **Model series 3000**

Model series 3000	Unit	Nominal torque	bi	Load directional (+/-)	in %	Rotational speed	
round shaft	Offic	bidirectional (+/-)	100 - 130	130 - 200	> 200	[rpm]	
Ø 15 mm		50		Set up opposite directional torque or		10.000	
y 15 mm		100	In specification		To recalibration	10.000	
Ø 25 mm	[Nm]	250				8 000	
y 25 mm	נוזווון	500			by NCTE	8.000	
Ø 40 mm		1.000		recalibration by NCTE	, -	F 000	
		2.000		DYNCIL		5.000	

Model series 3000	Unit	Nominal torque	bi	Load directional (+/-)	in %	Rotational speed
square shaft	Offic	bidirectional (+/-)	100 - 130	130 - 200	> 200	[rpm]
¾ inch		50	Set up opposite		_	10.000
¾ inch	[Nm]	250	In specification	directional torque or	To recalibration by NCTE	8.000
1 inch		1.000		recalibration by NCTE	BY NCIE	5.000

In case of an overload situation of the nominal torque it is possible to get the sensor back in specification. To do so please set up the same overload situation in the opposite direction. This means in case of an overload situation by 150 % positive load you can get the sensor back in specification by setting up a negative overload of 150 %.

NCTE is able to recalibrate any sensor until ultimate torque.





#### **Load characteristics**

Model series 3000 measuring range	Unit	Axial force [N] <sup>1</sup>	Lateral limit force [N]	Bending limit moment [Nm]
50 and 100		2.300	300	41,7
250 and 500	[Nm]	7.000	800	176
1.000 and 2.000		24.000	2.000	700

Each type of irregular stress can only be permitted with its given limit value (bending moment, lateral force or axial force, exceeding the nominal torque) if none of the others can occur. Otherwise the permitted limits must be reduced. If for instance 30 % of the limited bending moment and also 30 % of the limited lateral force are present, only 40 % of the limited axial force are permitted, provided that the nominal torque is not exceeded.

#### **Technical characteristics**

	Model		Serie	es 3000			
No.	Accuracy class <sup>2</sup>		0,2				
		Unit	Va	alue			
1	Linearity deviation incl. hysteresis		<:	±0,2			
2	Rotational Signal Uniformity (RSU)	%ME <sup>3</sup>	<:	±0,2			
3	Repeatability		< <u>+</u>	:0,05			
	Output signal in general	Unit	Value				
4	Frequency range, -3dB point, Bessel characteristics	Hz	2.	500			
5	Analog signal	V   mA	0 10	4 20			
6	Signal at torque = Zero <sup>4</sup>	V   mA	5	12			
7	Signal at positive nominal torque <sup>4</sup>	V   mA	9	19			
8	Signal at negative nominal torque <sup>4</sup>	V   mA	1	5			
9	Calibration parameter (normed) <sup>4</sup>	V/Nm mA/Nm	4 V/Measurement range	8 mA/Measurement range			
10	Error output	V   mA	10	22			
11	Output resistance	Ω		62			
	Effect of temperature	Unit	Va	alue			
12	Zero point drift over temperature	%/10 K	< 0,2				
13	Signal drift over temperature within nominal temperature range	%/10 K	<	0,5			

<sup>&</sup>lt;sup>1</sup> Direct acting axial force on the shaft. If the force affects the snap ring, just 50 % of the force is permitted.

<sup>&</sup>lt;sup>2</sup> The accuracy class implies that taken separately both the linearity deviation as well as the rotational signal uniformity are either lower than or equal to the value of the accuracy class.

<sup>&</sup>lt;sup>3</sup> %ME: related to a full scale measurement range.

<sup>&</sup>lt;sup>4</sup> Please check the exact data at the sensors calibration certificate.





	Power supply	Unit			Va	alue		
14	Supply voltage	28						
15	Current consumption (max.)	mA	150					
16	Start-up peak	mA			<	200		
17	Absolute max. supply voltage	VDC				30		
	General information	Unit			Va	alue		
18	Protection class according to EN 60529 <sup>5</sup>	IP			50	)/65		
19	Reference temperature	°C			+15	+35		
20	Operational temperature range	°C			-40	+85		
21	Storage temperature range	°C			-30	+85		
22	Bearing operating hours	h	approx. 20.000					
	Nominal rated torque M (bidirectional)	Nm	50	100	250	500	1.000	2.000
23	Weight	kg	-	1,4	2,5 6			6
24	Moment of inertia	kg mm²		5,9	59	,5	6	26
	EMI/EMC	Unit			Va	alue		
25	Tested standards							
26	EN 61000-6-3: 2007	-			Pa	ssed		
27	EN 55011: 2009 + A1: 2010 class B	-			Pa	ssed		
	Load limits <sup>6</sup>	Unit			Va	alue		
28	Maximum measurable torque	%			1	.10		
29	Maximum torque, related to nominal torque	%	300					
30	Ultimate torque	%			5	00		

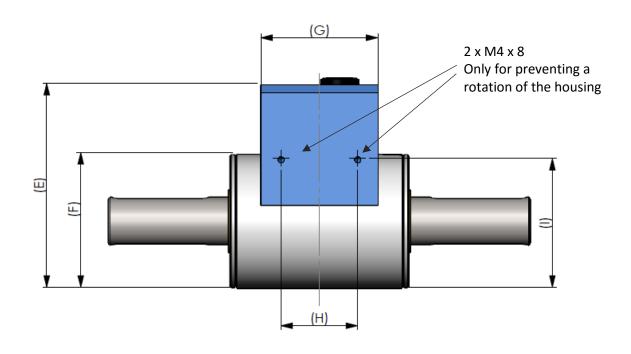
<sup>&</sup>lt;sup>5</sup> Wiring connected.

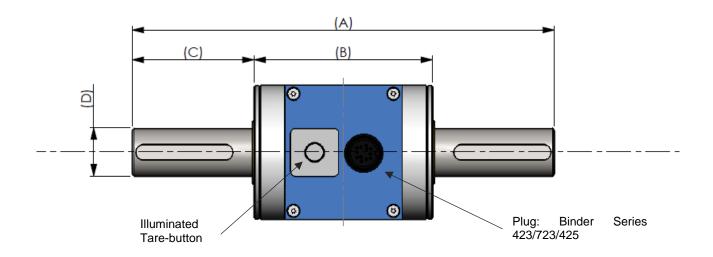
<sup>&</sup>lt;sup>6</sup> Based on the non-contact measurement principle the torque sensor is quite insensitive to bending and shearing forces. Self-aligning couplings are recommanded in case of dynamic loads.





## **Dimensions**





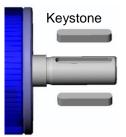






	Dimensions (in mm)												
	50 Nm	100 Nm	250 Nm	500 Nm	1.000 Nm	2.000 Nm							
Α	160	160	220	220	350	350							
В	93	93	101	101	130	130							
С	33,5	33,5	59,5	59,5	110	110							
D	15g6	15g6	25g6	25g6	40g6	40g6							
E	96	96	106	106	126	126							
F	60	60	70	70	90	90							
G	61	61	61	61	80	80							
Н	40	40	40	40	60	60							
I	57	57	67	67	87	87							

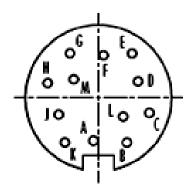
Dime	ensions ke	yway [mm	1]		Key stone- position		
Shaft	Width	Depth	Length	Height	Length	Amount	Distance L
Ø 15 mm	5N9	3	25,5	5	25	1	130,5
Ø 25 mm	8N9	4	50,5	7	50	2	165,5
Ø 40 mm	12N9	5	90,5	8	90	2	252,0







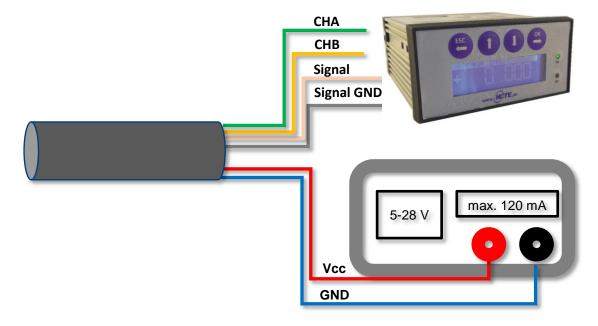
## **Connection plan**



Connector Power supply and outputs

Тур	Binder series 423/723/425 Item number: 09-0132-90-12 colour code according to DIN 47100										
Pin	Colour	Description	Value								
Α	White	Supply voltage V <sub>cc</sub>	11 V 28 V								
В	Brown	Ground GND	-								
С	Green	Analog Out	0 V 10 V								
D	Yellow	Analog GND	-								
Е	Grey	Analog Out	4 mA 20 mA								
F	Pink	Angle Ch A	0 V 5 V								
G	Blue	Angle Ch I	0 V 5 V								
Н	Red	Angle Ch B	0 V 5 V								
J	Black	-	-								
K	Violet	For internal use only	RX (TTL Pegel)								
L	Grey-Pink	For internal use only	RX (TTL Pegel)								
М	Red-Blue	Digital GND	-								

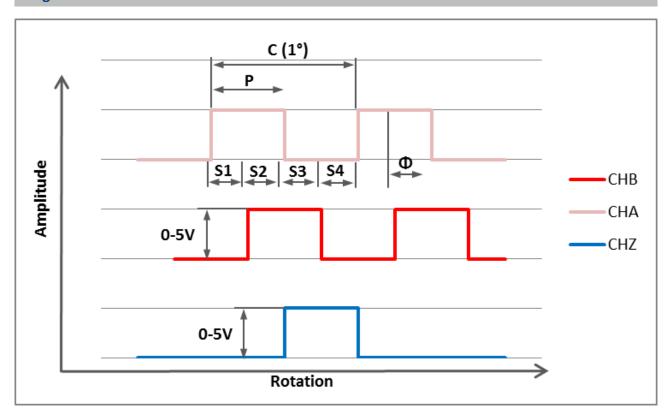
# Connection example:







## Angle sensor



Parameter	Min.	Тур.	Max.	Units			
High Level Output Voltage	2,4	5	-	V			
Low Level Output Voltage	0	-	0,4	V			
Parameter		Descr	ription				
С	One cycle of 360 CPR (degrees)						
Р	The duration of h	igh state of the ou	tput within one cy	cle.			
S		ectrical degress be ransition in Chann		in Channel A and			
Ф	The number of electrical degrees between the center of high state of Channel A and the Center of high state of Channel B.						





## **Order options**

Series 3	000	0 ac	cura	асу	0,2 %					Price			
	Me	asu	rem	ien	t rang	ge							
	5	0	Nn	Im including 5 m cable and calibration certificate									
	10	00	Nr	n ir	ncludi	ng 5	m	cable	and calibration certificate				
	25	50	Nn	n ir	ncludi	ng 5	m	cable	and calibration certificate				
	50	00	Nn	n ir	ncludi	ng 5	m	cable	and calibration certificate				
	1.0	00	Nn	n ir	ncludi	ng 5	m	cable	and calibration certificate				
	2.0	00	Nn	n ir	ncludi	ng 5	m	cable	and calibration certificate				
			An	ıgle	sens	or							
			0		With	out	ang	gle sen	sor				
			1		Angle	sei	nso	r 3600	CPR				
					Analo	og o	utp	out					
					Α	Vo	lta	ge out	put 0-10 V				
					S	Cu	rre	nt out	put 4-20 mA				
						Sh	aft	ends					
						C	)	Roun	d shaft with keystone				
						1	L	Squa	re shaft (available with 50/250/1.000 Nm)				
								Prote	ection class according to EN 60529				
				0 IP50									
					1 IP65								
3000													





Acces	sorie	S		Price							
	NCTI	E Read	lout Unit works with all NCTE Sensors								
	Torque sensor input: Voltage output 0-5 V and 0-10 V Order number: 400010-ATS001 A 1 angle encoder input, A/B USB interface, Windows software included SD card slot										
	S	Orde 1 ang USB	ue sensor input: current output 4-20 mA er number: 400010-ATS002 gle encoder input, A/B interface, Windows software included ard slot								
L		X	Customized couplings, price on request								





#### **Instruction manual**

## Scope of delivery

The torque sensor set consists of the sensor itself (signal pick-up and signal processing integrated into sensor housing), one **connecting cable** 5 m with a **soldered plug** (binder plug no. 99-0426-10-08), **key stones** (round shaft) and the calibration certificate.

Datasheets and instruction manuals are available at www.ncte.com.

#### Installation and removal

Make sure to install the sensor shafts exactly with the proper aligned connecting shafts. The key stone adapter/square endings of the connecting shafts are to be attached forceless to the corresponding ones of the sensor. No external axial force should be on the housing of the sensor from distortion. A maximum cable length of 5 m must not to be exceeded. Using a cable or connector other than supplied by **NCTE**, or a similar cable that is of a different length may affect the overall performance of the sensor.

Do not remove the shaft with torque applied to the sensor.

## Offset adjustment

If required the zero point output signal (5 V) can be adjusted by pressing the Tare-button. By factory default the sensor is set to 5 V at zero torque.

## Interface description

Mechanical connection:

The key stone adapters on both ends of the measurement shaft are intended for torque transmission.

#### Electrical connector:

On the sensor housing there is a 8-pin socket for the power supply and the signal output (chapter connection plan).

## Operation (in regular case or in optimal case)

Optimal measurement parameters can be achieved if the sensor is applied in accordance to the specification. By compliance with the specification the sensor works generally trouble-free and maintenance-free.

#### Irregular operation, measures against disturbance

The mechanical overload on the sensor (e. g. exceeding of maximum allowed torque or severe vibrations) may cause damage to the sensor and in consequence the incorrect signal output. In such cases please do not open the sensor. Contact **NCTE** directly for assistance.

#### Commissioning

After sensor installation pay attention to the following:

- The sensor may only be operated with a shielding.
- Switch on the power supply unit and check the supply voltage. Peak voltage must be avoided! Be sure to verify the power supply voltage before connecting the sensor!
- Connect the sensor to the power supply unit by using the delivered cable.
- Connect the sensor output to a high-resistance device such as an A/D converter, oscilloscope, PC measurement board. The sensor should be in mechanical unloaded state while connecting it.





#### Tare function and error indication:

Series 3000 contains a LED button on the housing surface. Pressing the button will set the signal output to 5 V. The illumination of the button serves as a function/malfunction indicator.

#### Functional indicator:

LED off: missing power supply or sensor is damaged

LED on: Sensor is ready.

#### Error indicator:

LED flashes: The sensor is not ready.

Flashing of LED can have several possible causes. Various causes are interpreted through a flash code. After each flash code the LED makes a short pause before repeating the code.

2x flashing: Magnet field sensors defective. 4x flashing: Electronics defective.

#### Shaft coating

The shafts are protected on both sides with a film of anticorrosion wax. We recommend to leave the protection permanent. As far as technologically needed, the coating can be removed with spirit/ethanol

## Handling and transportation

By handling, storage and transportation keep the sensor away from magnetic or electromagnetic fields which may exceed the maximal intensity defined from EMC (chapter technical characteristics) like degaussing machines.

## **Precautions**

- Do not open the sensor housing under any circumstances.
- Do not remove or loosen the locking rings on the shaft ends.
- Do not loosen or tighten the flange-mounting nut of the socket-connector (chapter dimensions).
- Use only a separate power supply for the sensor.
- Use the sensor only according to the specification (chapter technical characteristics).

#### Maintenance and overhaul

As part of your testing and measuring equipment management, we recommend regular checking of your testing and measuring equipment. Please also observe the corresponding standards and guidelines.

#### **Recommended NCTE maintenance plan**

Recalibration 12 month
Control of wiring, plug and shaft 12 month

#### Repairs

Repairs must be carried out exclusively by employees of NCTE AG. The sensor must be sent to the NCTE AG together with an RMA formula (Return Merchandise Authorization). You will receive an RMA formula via the NCTE service-hotline.

### Distributore italiano:



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