

# Torque Monitoring System with temperature detection

## TeIMAX

### for system applications

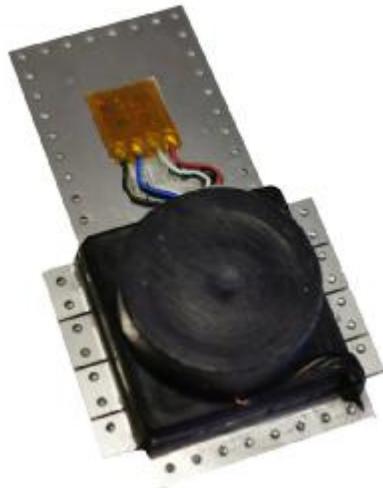


\*Patent pending

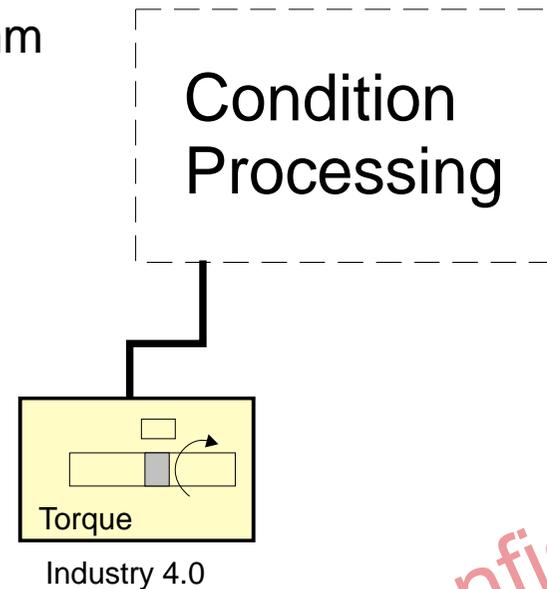
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## Application potential:

- Cost-effective, dynamic torque detection/monitoring on aggregates (gearboxes, motors, generators, etc.) in the context of Industry 4.0 without bonding and soldering process
- Innovative system concept for large distances between rotor and stator > 10 mm
- Suitable for new designs and integration into existing designs (retro-fit)
- Low axial space requirement for sensor cell < 18.1 mm



TeIMA-Torque Element



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## Features

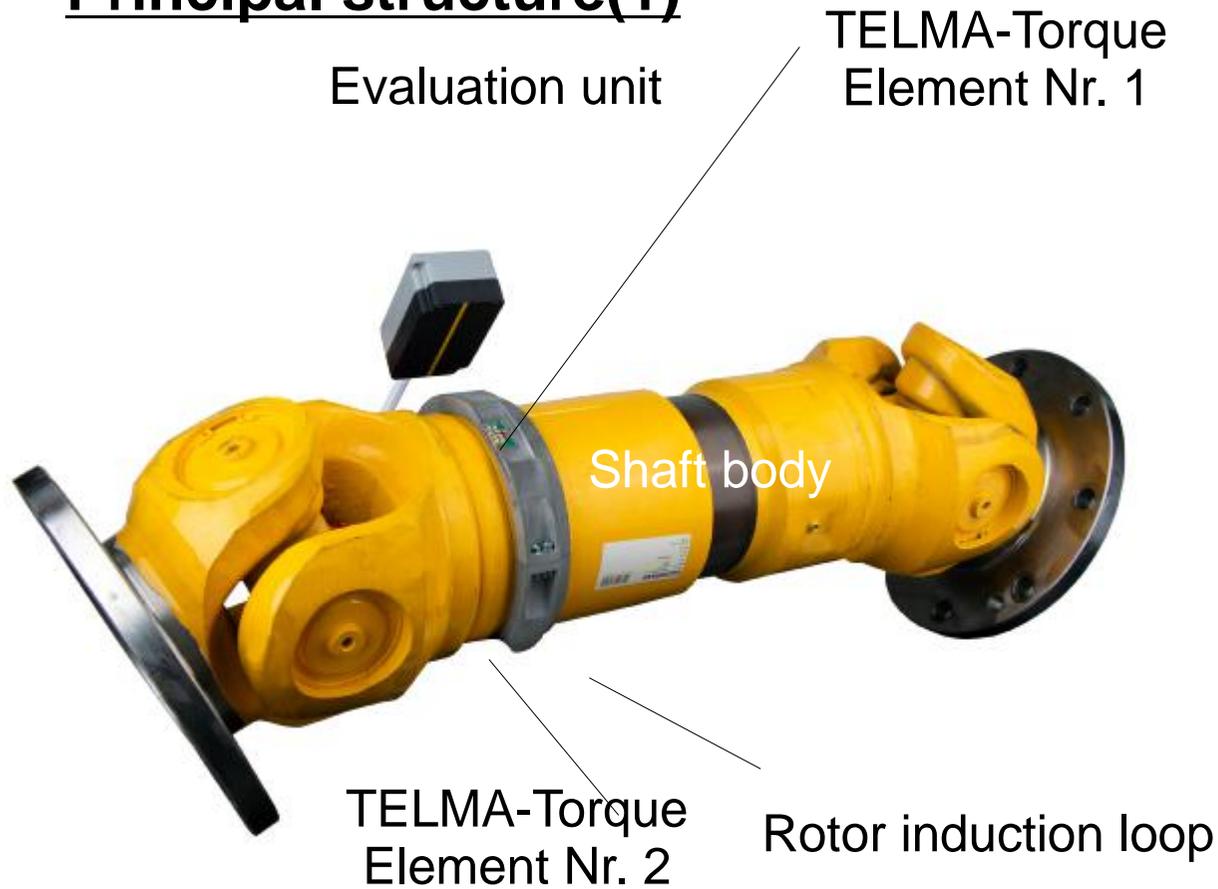


- Torque detection by telemetric torsion sensor (TelMAX-Torque) (dynamic acquisition of torque by means of strain gauge technology on rotating shaft)
- Additional temperature detection at each sensor element
- Shaft diameter 30..1000 mm through configurable rotor ring carrier
- Compact stator pick-up, large distance rotor - stator > 10 mm (ideal for cardan shaft applications)
- Compact TelMA torque element with integrated sensor and telemetry interface
- Easy assembly without affecting shaft strength in series using micro-welding technique
- No error-prone gluing or soldering and no wiring necessary
- Compensation of bending moment influence by mounting 2 elements
- High accuracy and measuring signal resolution
- Analogue or digital torque signal output
- Integrated speed measurement
- Digital, contactless signal transmission
- Maintenance-free operation



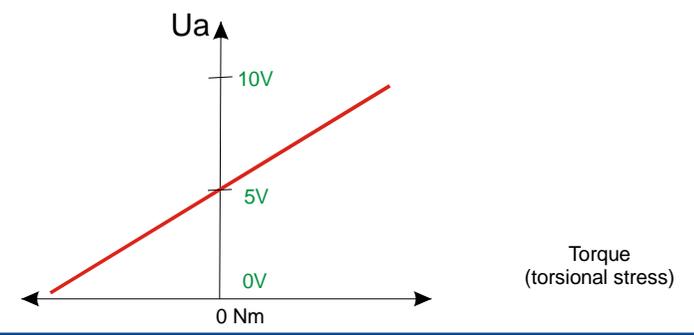
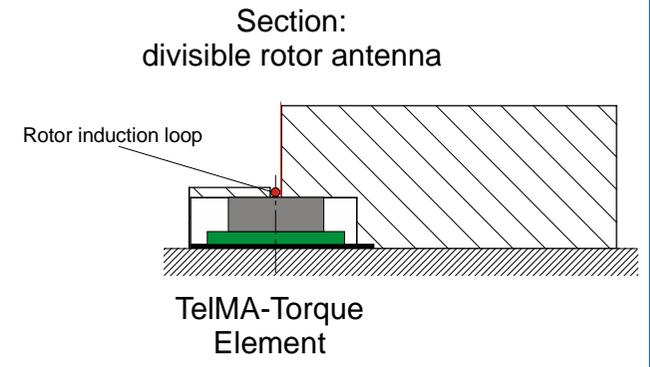
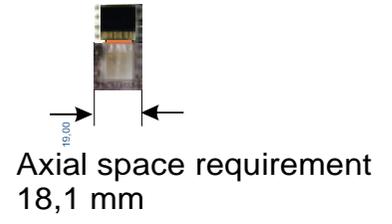
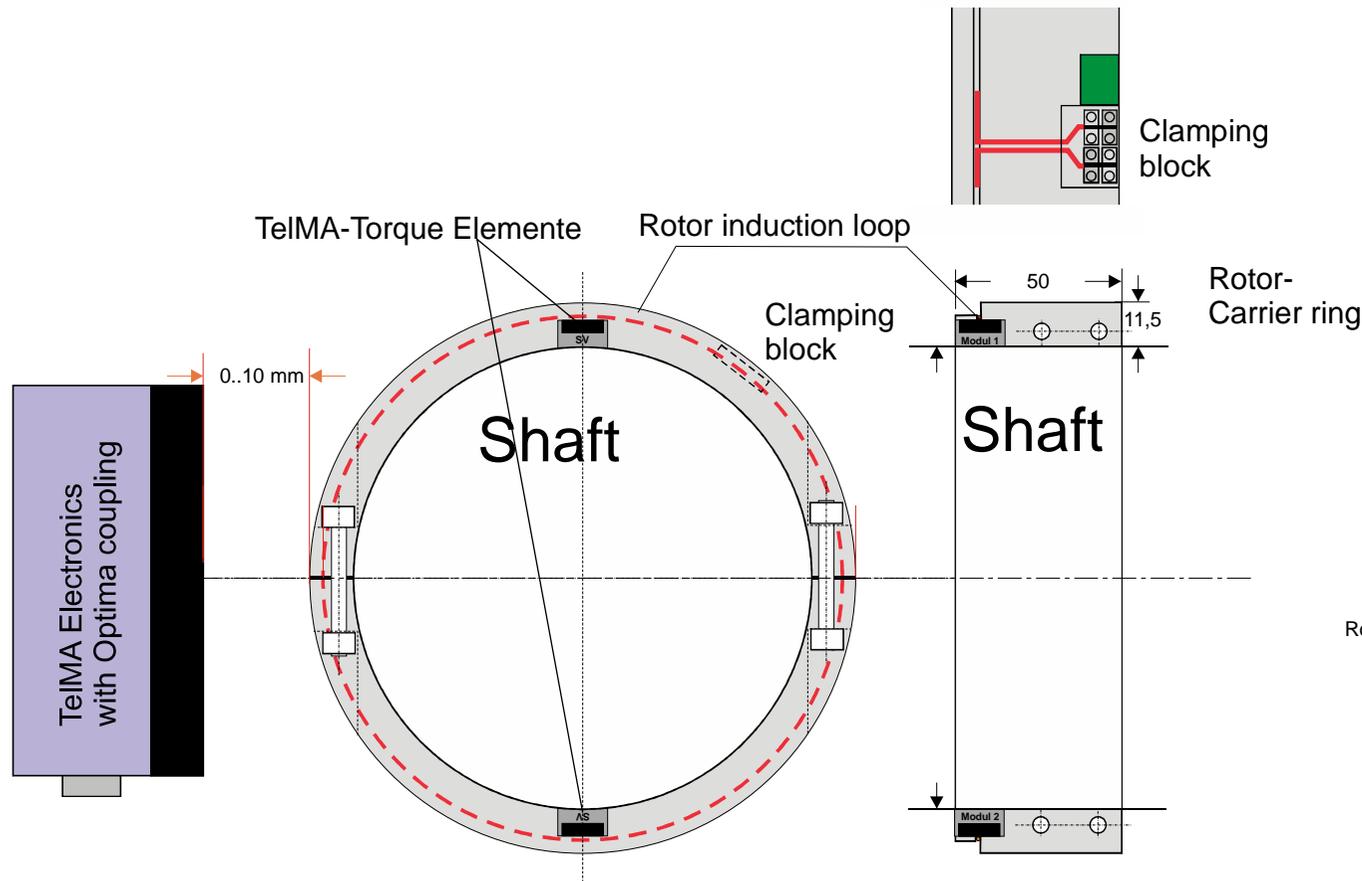
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## Principal structure(1)



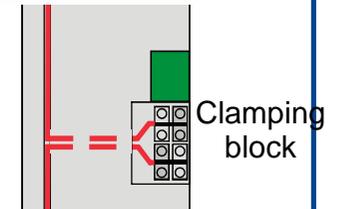
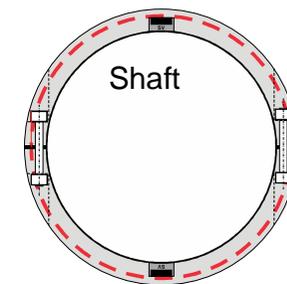
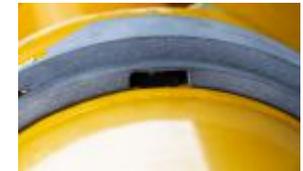
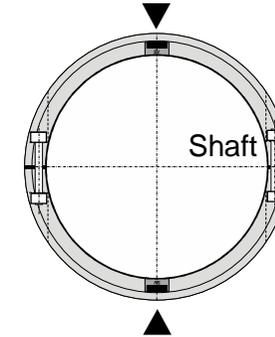
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# Principal structure (2)

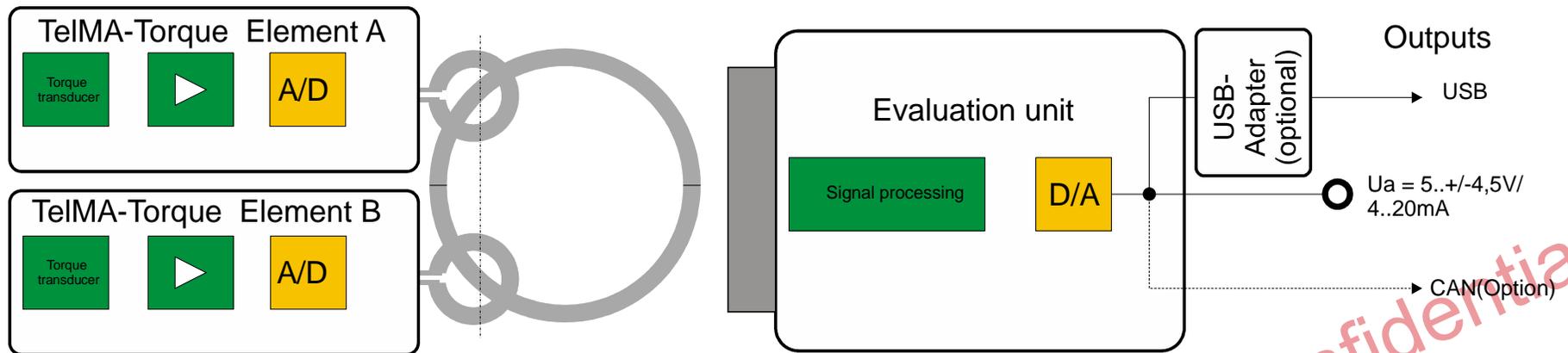
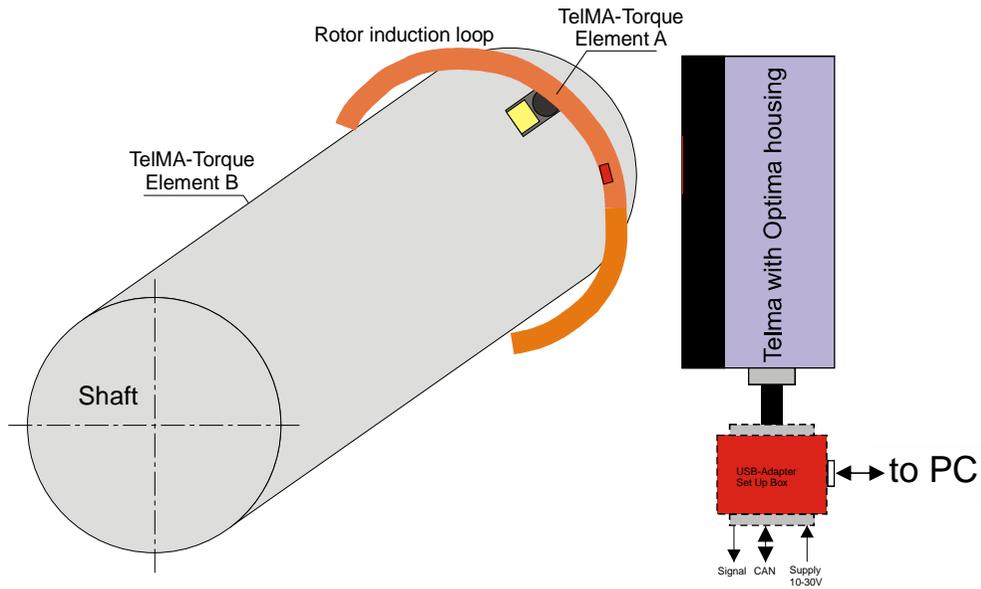


## Assembly sequence:

1. mounting TelMA torque elements on shaft
2. assembly of rotor support ring
3. insertion of rotor induction loop and connecting with terminal block
4. mounting Pick UP (stator)
5. finished

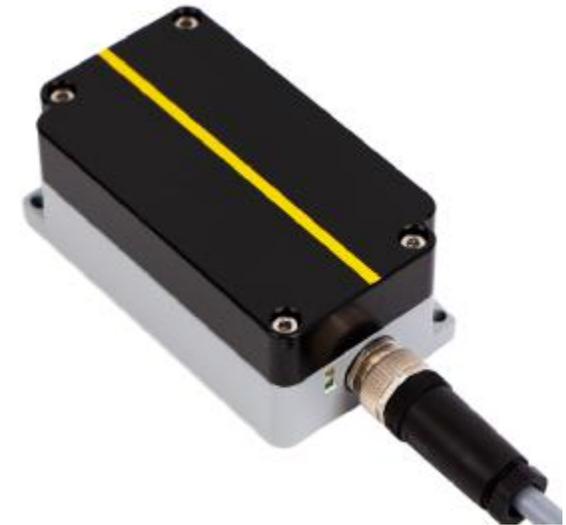
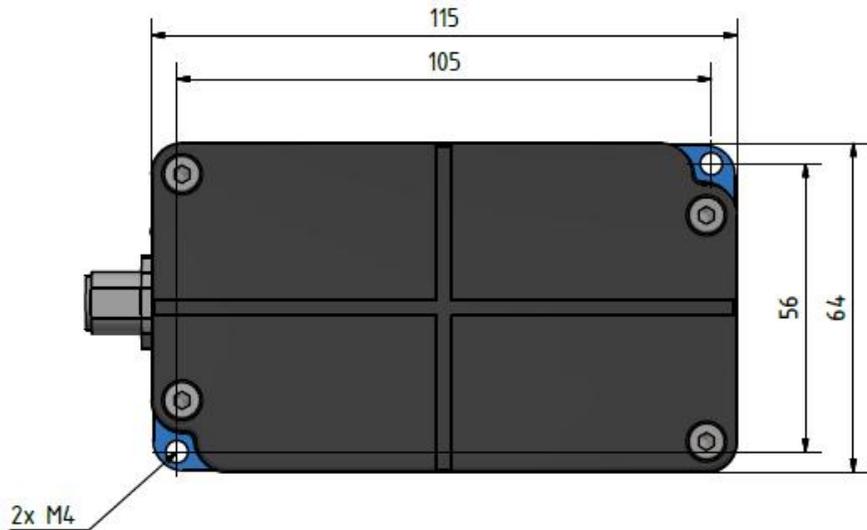


# Electrical construction



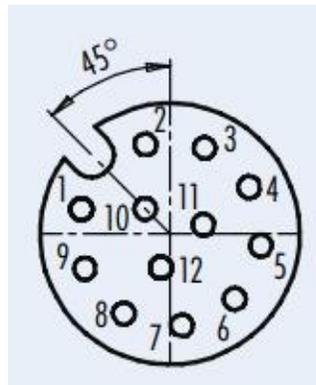
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# Stator unit (Industrial Version, IP67)



Pin

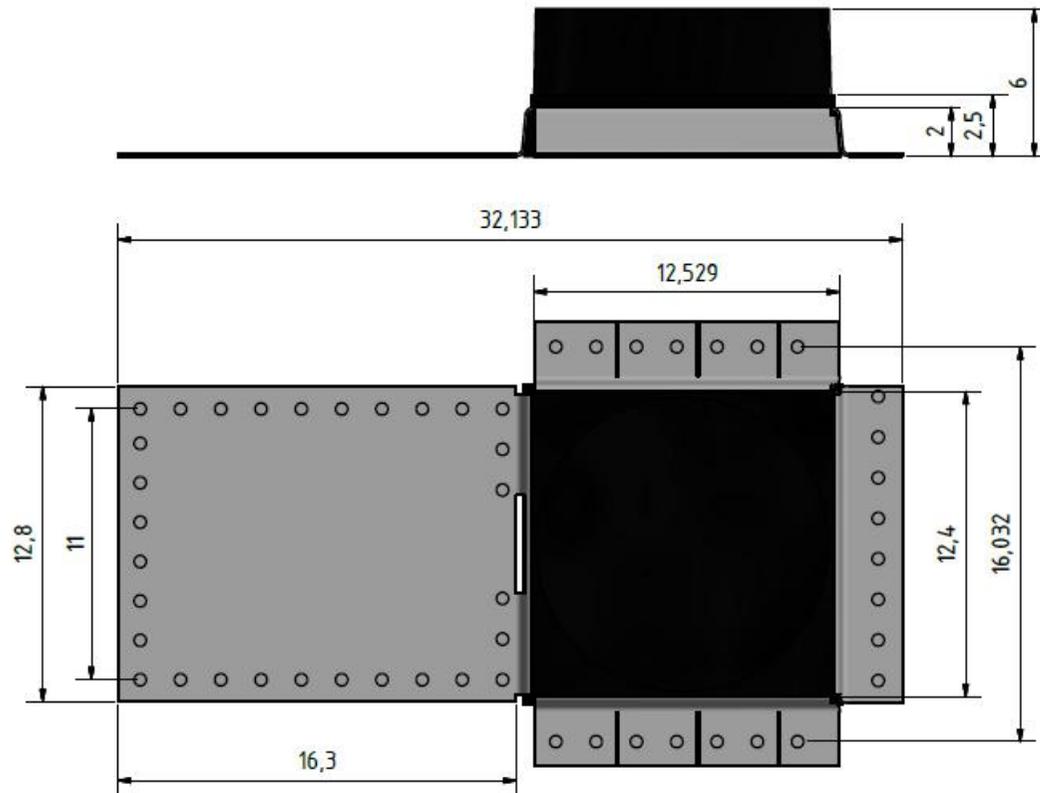
- 1 Analogue Out 2,5 +2,5 V/  
Analogue Out 4..20 mA
- 2 Analogue GND
- 3 KAL Signal
- 4 AutoZero
- 5 Power Supply GND
- 6 RPM (optional)
- 7 Power Supply 10-30VDC
- 8 TX/RX GND
- 9 TX out
- 10 RX In
- 11 CANL (optional)
- 12 CANH (optional)



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# TelMA-Torque Element

Dimensions:



Weight 10 g

- flexible carrier
- integrated sensor element
- integrated telemetry interface
- battery-free
- maintenance-free



Variant A  
(TelMA Torque with external sensor,  
high accuracy)



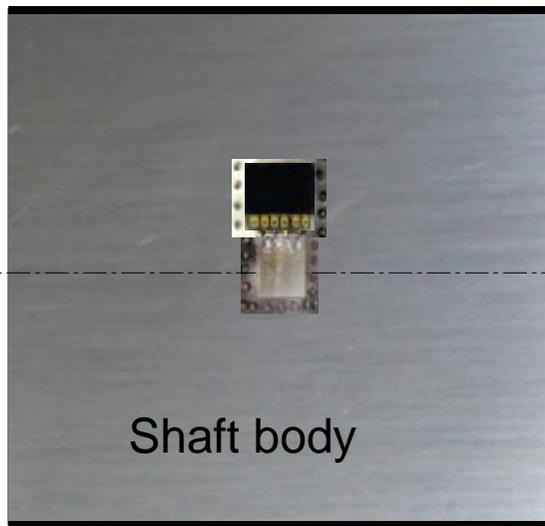
Variant B  
(TelMA Torque with covered sensor,  
for harsh environment)

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## Assembly process



TelMA Torque Element  
(with integrated telemetry interface)

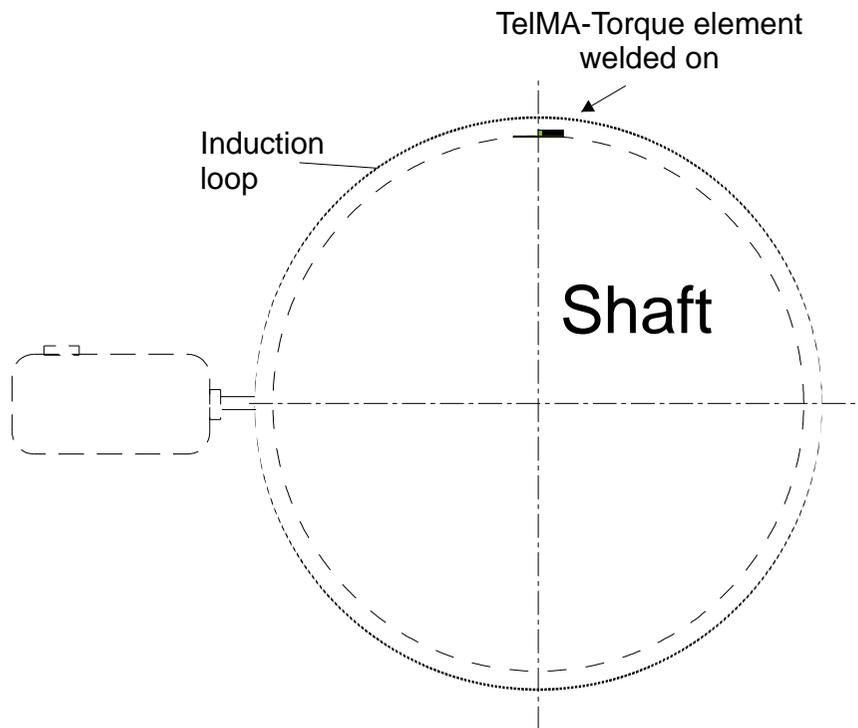


Shaft body

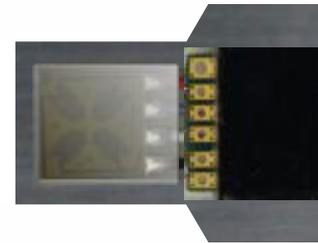
- easy assembly by means of micro spot welding process
- extremely robust assembly
- oil resistant
- short assembly time
- no soldering necessary
- no gluing necessary

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## Rotor kit for torque measurement with bending moment-free shafts



### TelMA-Torque Element

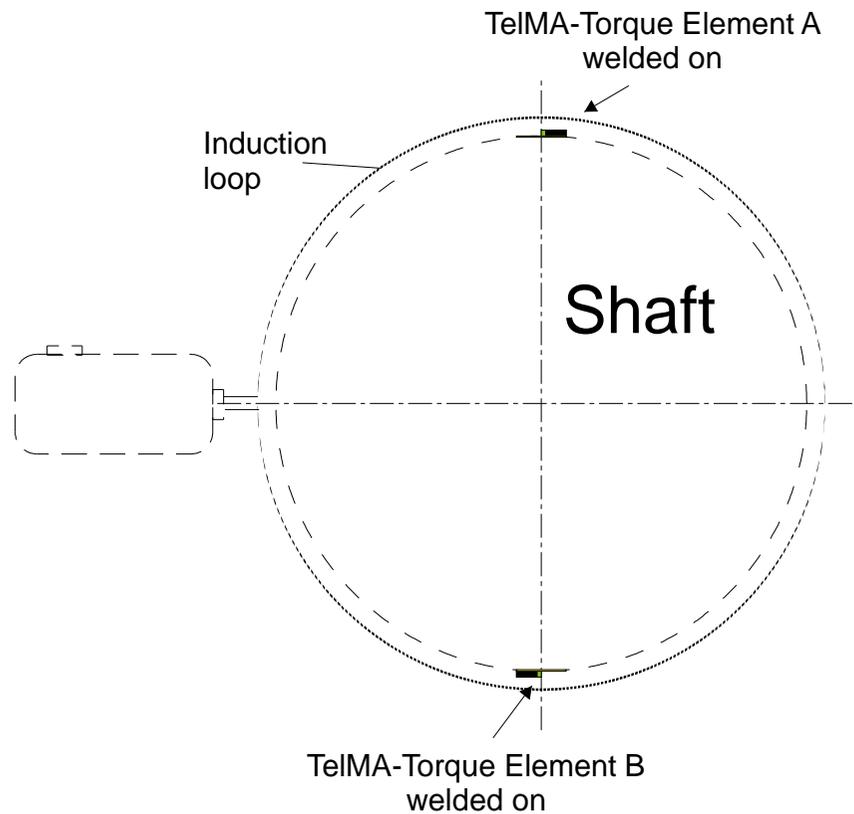


mounted axial

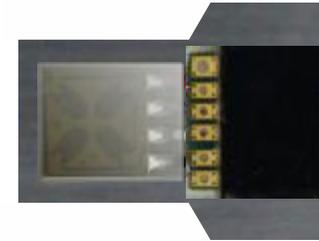
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## Rotor kit for torque measurement with bending moment compensation

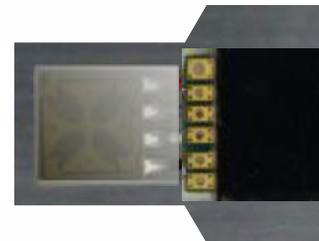
For shafts with additional bending moment load



TelMA-Torque Element A



TelMA-Torque Element B

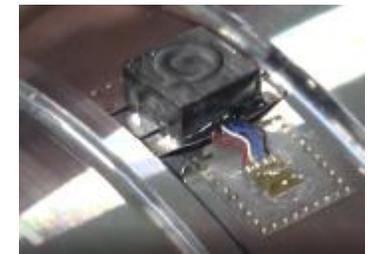
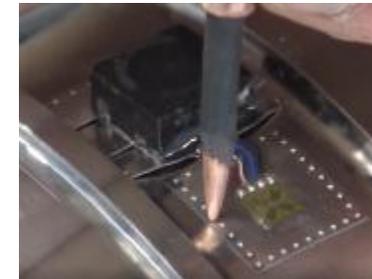
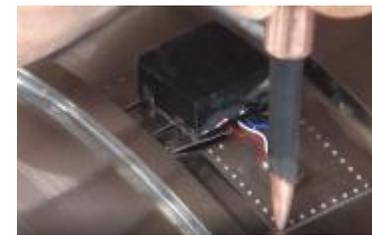
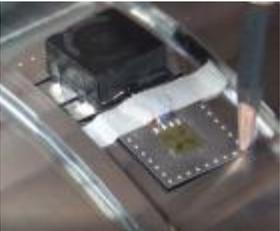
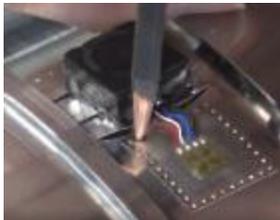
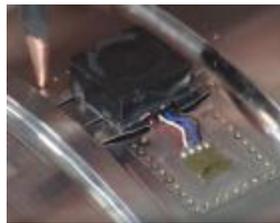
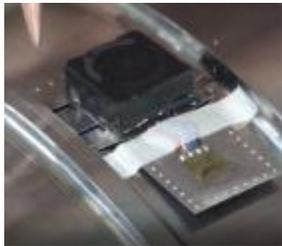


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# Simplest assembly TeIMA Torque Element

(Assembly by means of micro-welding process, without damaging the shaft properties - assembly time: approx. 2.5 minutes)

Start 00:00:00



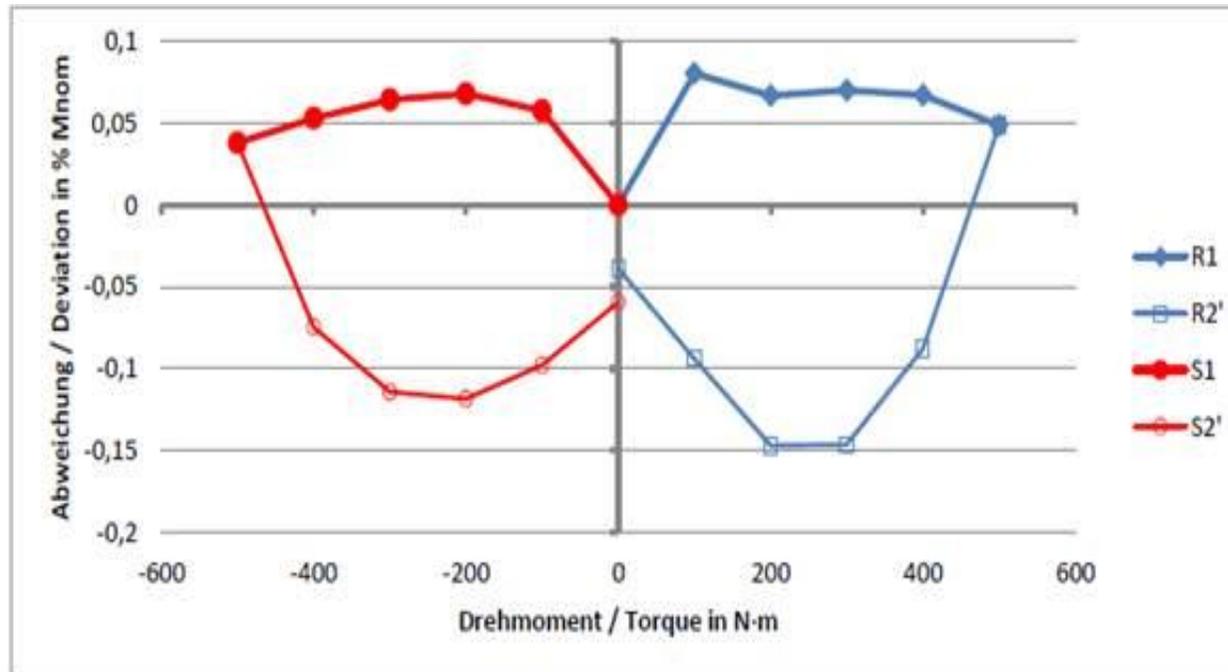
See also video

Manner Sensortelemetrie - TeIMA Torque  
Link zum Video auf YouTube  
<https://www.youtube.com/watch?v=Pckj1uNXHek>

End: 00:02:40

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## Linearity and hysteresis behaviour with bending moment compensation



>> excellent values if shaft material is of good quality

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## Advantages over magnetic methods

- large transmission distance (shaft - pick up)
- insensitive to magnetic fields
- no problem with shaft currents in hybrid or electric drives
- free choice of material (no need for ferromagnetic materials)
- no influence of shaft displacements/radial vibrations on the measuring signal
- good measuring signal quality even with low torsional stresses
- Higher accuracy by a factor of ten

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## Technical data - TelMAX Torque

Technology: Torque detection on shaft by means of TelMA torque sensor element(s) for long distance stator – rotor

Compensation of bending moment influences

Components: TelMA Torque Element(s), Rotor Induction Loop and Stator with Pick Up

TelMA-Torque Element

Telemetric sensor element based on strain gauge technology

Assembly: Micro welding technology

Signal resolution: 14 bit

Signal bandwidth: 1 kHz(-3dB)

Contactless transmission: inductive sensor telemetry PCM via rotor induction ring

max. zero drift (electronics): 0.05 %/10°K (with electronic drift compensation)

max. gain drift (electronics): 0.02%/10°K

max. linearity error (electronics): 0.001%.

Integrated integrity check (remote shunt calibration)

Electronically adjustable measuring range and auto zero adjustment

Applicable shaft diameter range: 30..500 mm

Max. Ambient temperature range (rotor): -25 to +120°C (option -45..160°C)

Max. radial load: 5 000 g

Rotor size (amplifier): 15 x 30 x 3.5 mm

Protection class depending on enclosure: IP42 ..IP67

Weight: 3,5g

Stator

AW with integrated compact pick-up, distance stator - rotor 0..> 20 mm, shaft diameter 23 ..1000 mm)

Power supply: 9..30 Volt +/- 10 %, 250 mA

Output signal (torque): 0..5 Volt (zero point at 2.5V)/ current 4 ..20 mA, CAN (option)

Residual ripple: 20 mVss

Integrated temperature recording (can only be evaluated via digital interface)

Optional integrated speed measurement

Max. Ambient temperature range (stator): -25 to +70°C (optionally 90 °C)

Housing size: 118 x 64 x 35 mm

Protection class: IP67

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